

CONFERENCE RECORD

SEVENTH ASILOMAR CONFERENCE ON CIRCUITS, SYSTEMS, AND COMPUTERS

EDITED BY

Sydney R. Parker
Naval Postgraduate School
Monterey, California

PAPERS PRESENTED

TUESDAY THROUGH THURSDAY NOVEMBER 27-29, 1973
ASILOMAR HOTEL & CONFERENCE GROUNDS - PACIFIC GROVE, CALIFORNIA

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THE CHARACTERISTIC POLYNOMIAL
OF GRAPH PRODUCTS[†]

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Abstract

An algebraic method is presented to calculate the characteristic polynomial of the product of graphs (boolean operations and expressions on graphs) in terms of the characteristic polynomials of the factor graphs.

1. INTRODUCTION

The characteristic polynomial of a graph may be used to classify it with respect to isomorphism, coverings, 1-factors, and graphical reconstructions. These topics have been studied by Collatz and Sinogowitz (1), Harary (2), Meyer (3), Mowshowitz (4), and Clarke (5).

Both Mowshowitz and Clarke approach the problem of calculating the coefficients of the characteristic polynomial from a combinatorial viewpoint, showing that the coefficients can be computed by counting the number of collections of disjoint directed (or undirected) cycles of specified length.

In this study we develop a method to compute the characteristic polynomial of graph products in terms of the factor graph polynomials. The approach adopted is algebraic rather than combinatorial and utilizes the eigenvalues of the factor graphs.

2. GRAPHS AND GRAPH PRODUCTS

2.1 Preliminaries

A *digraph* $D = (V, E)$ is an irreflexive binary relation on a finite set $V = V(D)$ of *vertices* of D ; the collection $E = E(D)$ of ordered pairs of vertices are called the *edges* of D . Let $|V|$ denote the cardinality of $V(D)$. A *graph* is a symmetric digraph.

The *adjacency matrix* $A = A(D)$ of a digraph is a binary-valued, $|V| \times |V|$ dimensional matrix defined by its i, j -th entry as:

$$a_{ij} = \begin{cases} 1, & \text{if } (v_i, v_j) \in E(D) \\ 0, & \text{otherwise} \end{cases}$$

for $1 \leq i, j \leq |V|$.

Let $\underline{n} = \{1, 2, \dots, n\}$. The complete graph $K_n = (\underline{n}, E)$ is a graph such that

$$E(K_n) = \{(i, j) \mid i, j \in \underline{n} \text{ \& } i \neq j\}$$

The *zero graph* $0_n = (\underline{n}, E)$ has an adjacency matrix which is the $n \times n$ dimensional zero matrix. The *identity graph* $I_n = (\underline{n}, E)$ is the identity relation on $n \times n$. Notice that the identity graph is a reflexive relation, contradicting the above definition of a digraph. We permit this special case because of its usefulness in the sequel.

Let $D_1 = (V, E_1)$ and $D_2 = (V, E_2)$ be digraphs. The sum $D_1 + D_2$ is defined as the sum modulo 2 of their adjacency matrices.

The sum $D_1 + D_2$ is said to be *edge-disjoint* if for no $1 \leq i, j \leq |V|$, $a_{ij}(D_1) = 1$ and $a_{ij}(D_2) = 1$.

The *complement* \bar{D} of a digraph D is the sum $\bar{D} = D + K_{|V(D)|}$.

2.2 Boolean Operations on Graphs

Harary and Wilcox (6) have made a thorough study of graph products, calling them boolean operations on graphs. A *boolean operation*, \circ , on an ordered pair of disjoint digraphs D_1 and D_2 yields a digraph $D = D_1 \circ D_2$ such that $V(D) = V(D_1) \times V(D_2)$ and $E(D)$ is expressed in terms of $E(D_1)$ and $E(D_2)$. Three basic operations are defined and all others are expressed in terms of these basic ones.

The *Kronecker product* $D = D_1 \otimes D_2$ (conjunction(6)) is a digraph such that for any two vertices $u = (u_1, u_2)$ and $v = (v_1, v_2)$ in $V(D) = V(D_1) \times V(D_2)$, the edge $(u, v) \in E(D)$ if $(u_1, v_1) \in E(D_1)$ and $(u_2, v_2) \in E(D_2)$. In terms of the adjacency matrices we have

[†] This research was sponsored in part by the BNDE.

$$A(D) = A(D_1) \otimes A(D_2)$$

where \otimes denotes the Kronecker (or tensor) product and is defined as follows: let A and B be $p_1 \times p_1$ and $p_2 \times p_2$ dimensional, binary-valued matrices, respectively. The Kronecker product $A \otimes B$ is the $p_1 p_2 \times p_1 p_2$ dimensional matrix of the form

$$A \otimes B = \begin{bmatrix} a_{11}B & a_{12}B & \dots & a_{1p_1}B \\ \vdots & \vdots & \ddots & \vdots \\ a_{p_1 1}B & a_{p_1 2}B & \dots & a_{p_1 p_1}B \end{bmatrix}$$

The Kronecker sum $D = D_1 \times D_2$ is a digraph such that for any two vertices $u = (u_1, u_2)$ and $v = (v_1, v_2)$ in $V(D)$, the edge $(u, v) \in E(D)$ if

$$[(u_1, v_1) \in E(D_1) \text{ and } u_2 = v_2] \text{ or}$$

$$[u_1 = v_1 \text{ and } (u_2, v_2) \in E(D_2)]$$

It is clear that if $p_1 = |V_1|$ and $p_2 = |V_2|$, then

$$D_1 \times D_2 = D_1 \otimes I_{p_2} + I_{p_1} \otimes D_2 \quad (1)$$

$$A(D_1 \times D_2) = A(D_1) \otimes I_{p_2} + I_{p_1} \otimes A(D_2) \quad (2)$$

The similarity between (1) and (2) is due to our notation. It should be noted that the equality of (1) is isomorphism while that of (2) denotes equality of matrices. Henceforth, the adjacency matrix notation will be used only when necessary.

The complete Kronecker sum $D = D_1 * D_2$ is the digraph

$$D_1 * D_2 = D_1 \otimes K_{p_2} + K_{p_1} \otimes D_2$$

where $p_1 = |V_1|$ and $p_2 = |V_2|$.

Table 1 below lists the important boolean operations of Harary and Wilcox in terms of the basic operations.

Table 1

Boolean Operation	Definition
Composition (7) (Lexicographic Product (8))	$D_1[D_2] = D_1 \otimes K_{p_2} + D_1 \times D_2$
Symmetric Difference	$D_1 \otimes D_2 = D_1 * D_2 + D_1 \times D_2$
Disjunction	$D_1 \vee D_2 = D_1 * D_2 + D_1 \times D_2 + D_1 \otimes D_2$
Rejection	$D_1 D_2 = \bar{D}_1 \otimes \bar{D}_2$
γ -product	$\overline{(D_1 \vee D_2)} = D_1 \times D_2 + D_1 \otimes D_2$

Lemma 1 The boolean operations $D_1 \times D_2$,

$\overline{(D_1 \vee D_2)}$ and $D_1[D_2]$ are composed of edge-disjoint sums of digraphs.

Proof: For the first two operations, it is sufficient to consider the γ -product since the Kronecker sum is contained therein. The adjacency matrix for the γ -product is of the form:

$$A(\overline{(D_1 \vee D_2)}) = A(D_1) \otimes I_{p_2} + I_{p_1} \otimes A(D_2) + A(D_1) \otimes A(D_2) \quad (3)$$

Without loss of generality, suppose that $p_1=4$ and

$$A(D_1) = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The partitioned form of the right hand side of (3) is

$$\begin{bmatrix} 0 & 0 & I_{p_2} & 0 \\ 0 & 0 & 0 & 0 \\ 0 & I_{p_2} & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} + \begin{bmatrix} A(D_2) & 0 & 0 & 0 \\ 0 & A(D_2) & 0 & 0 \\ 0 & 0 & A(D_2) & 0 \\ 0 & 0 & 0 & A(D_2) \end{bmatrix} + \begin{bmatrix} 0 & 0 & A(D_2) & 0 \\ 0 & 0 & 0 & 0 \\ 0 & A(D_2) & 0 & A(D_2) \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Performing the sums block by block we note that they are edge-disjoint.

In the case of the composition $D_1[D_2]$ we have

$$A(D_1[D_2]) = A(D_1 \otimes K_{p_2}) + A(D_1 \times D_2)$$

$$= A(D_1) \otimes A(K_{p_2}) + A(D_1) \otimes I_{p_2} + I_{p_1} \otimes A(D_2)$$

$$= A(D_1) \otimes (A(K_{p_2}) + I_{p_2}) + I_{p_1} \otimes A(D_2)$$

$$A(D_1[D_2]) = A(D_1) \otimes J_{p_2} + I_{p_1} \otimes A(D_2) \quad (4)$$

where $J_{p_2} = A(K_{p_2}) + I_{p_2}$. Notice that J_{p_2} is the edge-disjoint sum of graphs. The partitioned form of (4) (with $p_1 = 4$ and $A(D_1)$ as above) is

$$\begin{bmatrix} 0 & 0 & J_{p_2} & 0 \\ 0 & 0 & 0 & 0 \\ 0 & J_{p_2} & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} + \begin{bmatrix} A(D_2) & 0 & 0 & 0 \\ 0 & A(D_2) & 0 & 0 \\ 0 & 0 & A(D_2) & 0 \\ 0 & 0 & 0 & A(D_2) \end{bmatrix}$$

Clearly, the block by block sums are edge-disjoint and the conclusion follows.

Q.E.D.

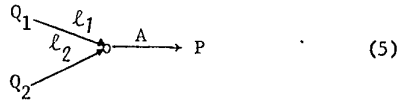
3. ALGORITHMS AND CHARACTERISTIC POLYNOMIALS

3.1 TREE ALGORITHMS

An algorithm $Q \xrightarrow{A} P$ is an effectively computable process which maps object Q to object P . The composition and cartesian product of algorithms are analogous to those of functions; if

$$Q \xrightarrow{A_1} P \text{ and } P \xrightarrow{A_2} R \text{ then } Q \xrightarrow{A_2 \circ A_1} R$$

and $Q \times P \xrightarrow{A_1 \times A_2} P \times R$. If the "domain" of an algorithm consists of more than one object, then we write $Q_1 \times Q_2 \xrightarrow{A} P$, and



where \circ denotes that $Q_1 \times Q_2$ is the domain of A , and l_i ($i = 1, 2$) denote the injections

$$Q_1 \xrightarrow{l_1} Q_1 \cup Q_2 \xleftarrow{l_2} Q_2$$

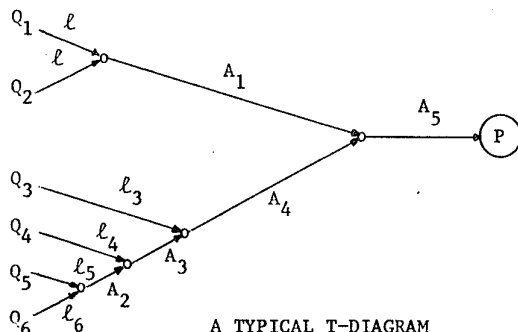
A tree algorithm (T-algorithm) on n objects

$$Q_1 \times Q_2 \times \dots \times Q_n \xrightarrow{T} P$$

is an algorithm which is the composition of a finite number of algorithms such that:

- (1) T is (represented by) a rooted, directed, labelled, binary tree (9).
- (2) P is the root of T .
- (3) The arc labels of T are algorithm names:
- (4) The "leaves" of T are the objects $Q_i, i \in \underline{n}$.
- (5) The internal vertices denote \circ as in (5), or algorithm objects.

The T -diagram for a typical T-algorithm is depicted in Figure 1.



A TYPICAL T-DIAGRAM
Figure 1

3.2 EIGENVALUES, POLYNOMIALS AND ϕ -ALGORITHMS

The characteristic polynomial, $C(D)$, of a digraph D is $C(D) = \det(A(D) - Ix)$, where the determinant is calculated over the ring of integer numbers.

The eigenvalues of D are the roots of $C(D)$, calculated over the field of complex numbers.

Algorithm A: (10, p. 55) Let $C(D)$ be of the form

$$C(D) = x^n - c_1 x^{n-1} + c_2 x^{n-2} - \dots + (-1)^n c_n$$

and

$$\lambda(D) = \{\lambda_1, \lambda_2, \dots, \lambda_n\}$$

then the r -th coefficient c_r of $C(D)$ is the sum of all products of the n eigenvalues taken r at a time.

We denote Algorithm A as $\lambda(D) \xrightarrow{A} C(D)$.

Fact Given $D = (V, E)$ a digraph and $\lambda(D)$, the coefficient c_1 of $C(D)$ is zero. (Here we exclude identity graphs).

This result is immediate from the identity (10)

$$c_1 = \sum_{i=1}^n \lambda_i \doteq \text{trace}(A(D)) = \sum_{j=1}^n a_{jj} = 0$$

It is worthwhile to note that if D is a digraph, $A(D)$ is binary-valued, the coefficients of $C(D)$ are integers, and the eigenvalues of D are either real or complex numbers. Although $A(D)$ is binary-valued, at times we will treat it as complex-valued, as in the next few algorithms.

Algorithm A_1^* : (11) Let $G = (V, E)$ be a graph. Since $A(G)$ is a real symmetric matrix whose eigenvalues are real, there exists an algorithm

$$A(G) \xrightarrow{A_1} \Lambda(G), \text{ where } \Lambda(G) \text{ is the diagonal matrix consisting of the eigenvalues of } G. \text{ Let}$$

$$A(G) \xrightarrow{A_1^*} \lambda(G)$$

Algorithm A_2^* : (10) Let $D = (V, E)$ be a digraph.

There exists an algorithm $A(D) \xrightarrow{A_2} J(D)$, where $J(D)$ is the block diagonal Jordan form matrix whose diagonal consists of the eigenvalues of D . Let

$$A(D) \xrightarrow{A_2^*} \lambda(D)$$

The third algorithm relies on a theorem whose proof can be found in Lancaster (10, p. 259).

Theorem 1 Let $\phi(x, y)$ be a polynomial in x and y with complex coefficients c_{ij} of the form

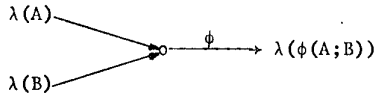
$$\phi(x, y) = \sum_{i, j=0}^p c_{ij} x^i y^j \quad (6)$$

Suppose A and B are complex-valued $n \times n$ and $m \times m$ matrices, respectively. Consider the $mn \times mn$ matrix of the form

$$\phi(A;B) = \sum_{i,j=0}^P c_{ij} A^i \otimes B^j \quad (7)$$

If $\lambda(A) = \{\lambda_1, \dots, \lambda_n\}$ and $\lambda(B) = \{u_1, \dots, u_m\}$ then
 $\lambda(\phi(A;B)) = \{\phi(\lambda_r, u_s) \mid \lambda_r \in \lambda(A), u_s \in \lambda(B), r \in \underline{n}, s \in \underline{m}\}$.

Algorithm ϕ : Given $\lambda(A), \lambda(B)$ and $\phi(x,y)$, there exists a T-algorithm which computes $\lambda(\phi(A;B))$.

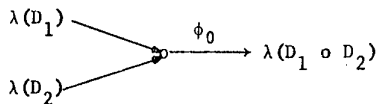


4. THE CHARACTERISTIC POLYNOMIAL OF GRAPH PRODUCTS

4.1 ϕ -POLYNOMIALS FOR BOOLEAN OPERATIONS

We are now prepared to study the characteristic polynomial of the product of graphs. Our goal is to apply the "algebraic machinery" developed for complex numbers to graphs. We begin by characterizing those boolean operations which have an associated ϕ -polynomial.

Lemma 2 Let D_1 and D_2 be digraphs with $\lambda(D_1)$ and $\lambda(D_2)$ given. Let $\Gamma = \{\otimes, x, \gamma\text{-product}\}$. For any boolean operation o in Γ , there exists a T-algorithm ϕ which computes $\lambda(D_1 o D_2)$, i.e., for $o \in \Gamma$.



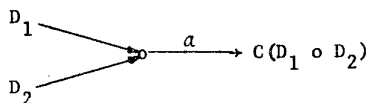
Proof: From the definitions of the Kronecker product, Kronecker sum, and γ -product, one immediately notices that the ϕ -polynomials are $\phi_{\otimes} = xy$, $\phi_x = x+y$, and $\phi_{\gamma} = x+y+xy$, respectively.

For those operations whose ϕ -polynomials involve sums, we must insure that the sum of corresponding digraphs is edge-disjoint, thereby allowing modulo 2 sums to also be valid over the complex numbers. By Lemma 1, we see that this is the case for the Kronecker sum and γ -product.

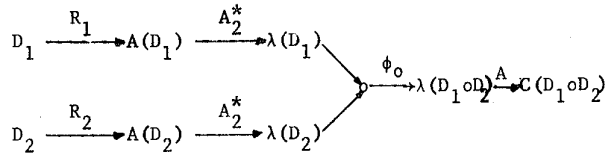
Q.E.D.

We conclude that those boolean operations which involve the sum of digraphs and admit ϕ -polynomials also preserve edge-disjointness. Note however that the composition operation $D_1[D_2]$ preserves edge-disjointness, but has no associated ϕ -polynomial.

Theorem 3 Let D_1 and D_2 be digraphs. For any $o \in \Gamma$, there exists a T-algorithm a of the form



Proof: The T-diagram below defines a in terms of previously defined algorithms:



$$a = A \circ \phi_0 \circ (A_2^* \times A_2^*) \circ (R_1 \times R_2)$$

where R_i maps D_i to its adjacency matrix $A(D_i)$, $i = 1, 2$.

Q.E.D.

4.2 BOOLEAN EXPRESSIONS AND T-REALIZABILITY

An obvious extension of Theorem 3 is to include the composition of ϕ -algorithms. For this we introduce the notion of a boolean expression of digraphs. The definition is recursive and follows that of Even (12, p. 140).

Let $\mathcal{D} = \{D_i \mid i \in \underline{k}\}$ denote a finite set of digraphs and Γ^* a set of boolean operations. Let $B(\mathcal{D}, \Gamma^*)$ denote the set of *boolean expressions*, each consisting of a sequence of boolean operations from Γ^* on digraphs in \mathcal{D} .

A *well-formed* boolean expression satisfies the following conditions:

- (1) The empty expression is well-formed.
- (2) If A and B are well-formed, then for any $o \in \Gamma^*$, $A o B$ is well-formed.
- (3) If A is well-formed, then so is (A) .
- (4) There are no other well-formed expressions.

Henceforth, we consider only well-formed boolean expressions. It is clear, from Table 1 that every boolean expression can be expressed in its *normal form*, which consists of the sum of the Kronecker products of digraphs. The normal form of a boolean expression is *disjoint* if the sum of Kronecker products of digraphs is edge-disjoint.

Lastly, the characteristic polynomial of a boolean expression is *T-realizable* if there exists a T-algorithm consisting of the composition of T-algorithms ϕ such that the root of T is the characteristic polynomial of the expression.

Example 1. Let $B = ((D_1 \times D_2) \vee D_3) \otimes D_4$

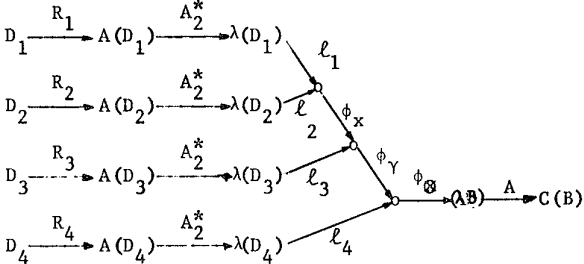
The normal form for B is

$$\begin{aligned} NF(B) &= ((D_1 \times D_2) \times D_3 + (D_1 \times D_2) \otimes D_3) \otimes D_4 \\ &= ((D_1 \otimes I_{P_2} + I_{P_1} \otimes D_2) \times D_3 + (D_1 \otimes I_{P_2} + \\ &\quad + I_{P_1} \otimes D_2) \otimes D_3) \otimes D_4 \\ &= ((D_1 \otimes I_{P_2} + I_{P_1} \otimes D_2) \otimes I_{P_3} + I_{P_1 P_2} \otimes D_3 + \\ &\quad + D_1 \otimes I_{P_2} \otimes D_3 + I_{P_1} \otimes D_2 \otimes D_3) \otimes D_4 \end{aligned}$$

$$\begin{aligned}
&= D_1 \otimes I_{P_2} \otimes I_{P_3} \otimes D_4 + I_{P_1} \otimes D_2 \otimes I_{P_3} \otimes D_4 + \\
&I_{P_1} \otimes I_{P_2} \otimes D_3 \otimes D_4 + D_1 \otimes I_{P_2} \otimes D_3 \otimes D_4 + \\
&+ I_{P_1} \otimes D_2 \otimes D_3 \otimes D_4
\end{aligned}$$

It can be verified that $NF(B)$ is disjoint. Moreover, this can be ascertained directly from B by noting that x and the γ -product have disjoint normal forms.

Clearly $C(B)$ is T-realizable and has the T - diagram.



The next two theorems characterize T-realizable boolean expressions on digraphs.

Theorem 4 Every T-realizable, well-formed boolean expression $B \in \mathcal{B}(D, \Gamma^*)$ has a disjoint normal form.

Proof: If B is T-realizable then all ϕ -algorithms involving sums of digraphs must preserve edge-disjointness, as do their composition. Thus, the sequence of expansions which leads to the normal form for B must also preserve edge-disjointness thereby insuring that B has a disjoint normal form. Q.E.D.

The previous result provides a necessary condition for T-realizability. However, well-formed boolean expressions exist, take for example $B = D_1[D_2]$, which are not T-realizable. If we restrict Γ^* to be the set $\{\otimes, x, \gamma\}$, then we obtain the

Theorem 5 Let $\Gamma^* = \{\otimes, x, \gamma\}$. The characteristic polynomial of every well-formed boolean expression $B \in \mathcal{B}(D, \Gamma^*)$ is T-realizable.

Proof: The conclusion is a direct consequence of Lemmas 1 and 2 and Theorem 4.

4.3 T-REALIZABILITY FOR COMPLETE GRAPHS

It is of interest to include as many boolean operations as possible in Γ^* while insuring T-realizability. For the case of well-formed boolean expressions on complete graphs, several operations may be added to Γ^* .

Lemma 3 Let K_{P_1} and K_{P_2} be complete graphs. Then

- (1) $K_{P_1} \times K_{P_2} = K_{P_1} \otimes K_{P_2}$
- (2) $K_{P_1}[\overline{K}_{P_2}] = K_{P_1} \vee K_{P_2} = (\overline{K}_{P_1} \vee \overline{K}_{P_2})$
- (3) $K_{P_1 P_2} = K_{P_1}[\overline{K}_{P_2}] = K_{P_2}[\overline{K}_{P_1}]$
- (4) $K_{P_1} * K_{P_2} = 0_{P_1 P_2}$

Proof: The results can be verified by direct substitution in Table 1 and by comparing adjacency matrices.

Theorem 6 Let $m \geq 2$ be a natural number. Then there exists a T-algorithm a^* of the form

$$K_{P_1} \times K_{P_2} \times \dots \times K_{P_k} \xrightarrow{a^*} C(K_m)$$

where $p_i, 1 \leq i \leq k$ are prime numbers.

Proof: Every natural number m has a decomposition as the product of powers of primes,

$$m = p_1^{e_1} \cdot p_2^{e_2} \cdot \dots \cdot p_k^{e_k}$$

where $2 \leq p_1 < p_2 < \dots < p_k$.

By repeated use of Lemma 3.3, we obtain

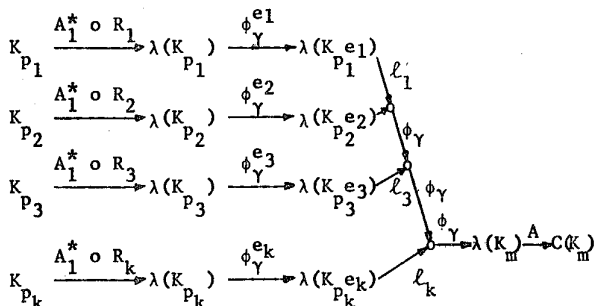
$$K_m = K_{P_1} e_1 \left[K_{P_2} e_2 \right] \dots K_{P_{k-1}} e_{k-1} \left[K_{P_k} e_k \right] \dots$$

where for each $i \in \underline{k}$

$$K_{P_i} e_i = K_{P_i} \left[K_{P_i} \left[\dots K_{P_i} \left[K_{P_i} \right] \dots \right] e_i \text{-times} \right]$$

From Lemma 3.2 we know that the composition of complete graphs preserves edge-disjointness, thereby admitting a T-realization for $C(K_m)$. Clearly, the tree will be composed of ϕ_γ -algorithms. For simplicity, let $\phi_\gamma^{e_i}$ denote the algorithm

$\lambda(K_{P_i}) \xrightarrow{\phi_\gamma^{e_i}} \lambda(K_{P_i} e_i)$. The T-diagram for $C(K_m)$ is



Q.E.D.

Theorem 7 Let $K = \{K_i \mid p_i \text{ a prime and } i \in n\}$ be a finite set of complete graphs. Let $\bar{\Gamma} = \{ \otimes, \times, \gamma, [], \oplus, \vee \}$. The characteristic polynomial of every well-formed boolean expression $B \in B(K, \bar{\Gamma})$ is T-realizable. $\bar{\sim}$

Proof: The conclusion is a direct consequence of Lemma 3 and Theorem 5.

5. CONCLUDING REMARKS

We have presented an algebraic method involving tree algorithms which computes the characteristic polynomial of graph products (well-formed boolean expressions) in terms of the eigenvalues (and hence the characteristic polynomials) of the factor graphs. Necessary and sufficient conditions have been presented for the T-realizability of the characteristic polynomial of certain classes of boolean expressions.

Sabidussi (13) has shown that every connected graph of finite type has a unique prime factor decomposition with respect to the Kronecker sum operation. This decomposition is T-realizable, and it would be of interest to implement his decomposition as well as the T-algorithms on the computer to compare the proposed method with a direct method, such as Mowshowitz's, in terms of speed, accuracy, and store requirements.

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