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A SLIP APPLICATION: THE CONSTRUCTION OF TURING MACHINES

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A SLIP Application: the Construction of Turing Machines

1. Introduction

In the first place we will try to define, in a concise way, what is meant by a Turing machine [1], and we will also present one of the possible formulations. A Turing machine is a device composed of a read and write head and a tape unit, of arbitrary length. Fig. 1 below shows how it looks like, for the purpose of this paper.

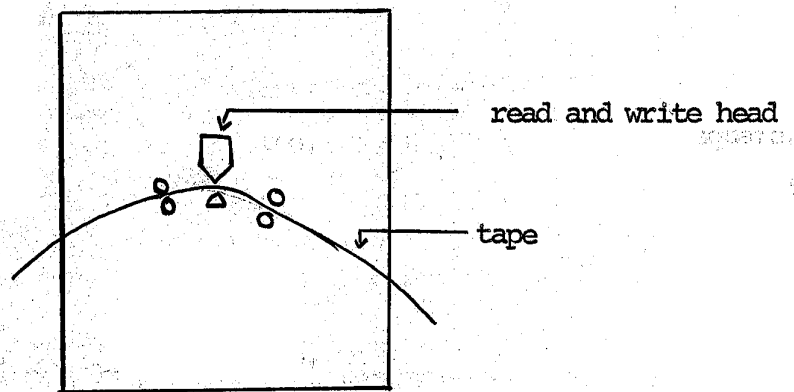


Fig. 1

We imagine the tape subdivided into squares, in such a way that each square can contain only one symbol.

The following operations are admitted on Turing machines:

- a) Write a symbol on the tape;
- b) Right displacement relative to tape;
- c) Left displacement relative to tape.

The following is one of the formulations of a Turing machine:

Definition:

A Turing machine is a set of quadruples of the form:

- (i) $q_i s_j s_k q_l$
- (ii) $q_i s_j R q_l$
- (iii) $q_i s_j L q_l$

Remark:

$q_i s_j s_k q_l$ - means that the machine is at the state q_i , the read and write head reads the symbol s_j , writes the symbol s_k , and the machine turns to state q_l .

$q_i s_j R q_l$ - is similar to the above, with the difference that instead of writing a symbol the head moves to the right (left), or the tape moves to the left (right).

2. Numerical Computation

Let $x = (x_1, x_2, \dots, x_n)$ be a n-pla, where each component represents a certain address relative to a tape, i.e., each is a delimiter of a certain area of the tape; also let \$ (dollar sign) be a pointer to the beginning of the tape. Each integer number is represented either by a sequence of digits "1" or by a sequence of "|": for example, the number 5 is represented by |||||. The tape has the following appearance:

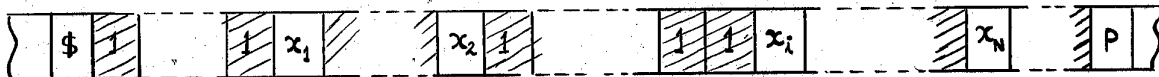


Fig. 2

3. A Turing machine that determines the successor of a component

Let us suppose that during the computation of a function $f: N^n \rightarrow N$ the machine is at the state q_m and that the read and write head is positioned in any part of the magnetic tape. The set of quadruples, below, simulates the operation $x_i + 1 \rightarrow x_i$.

- 1. $q_m \bar{\alpha} L q_m$ Looks for the beginning of the tape, replaces α for x_i (pointer to the address of the i.th component), and displaces α a square left, passing to
- 2. $q_m \bar{\alpha} x_i q_{m1}$

- 3. $q_{m1} x_i L q_{m1}$
- 4. $q_{m1} B \alpha q_{m1}$
- 5. $q_{m1} \alpha R q_{m2}$
- 6. $q_{m2} \bar{x}_i R q_{m2}$
- 7. $q_{m2} x_i R q_{m3}$
- 8. $q_{m2} \bar{x}_i R q_{m3}$
- 9. $q_{m3} x_i L q_{m4}$
- 10. $q_{m4} B L q_{m4}$
- 11. $q_{m4} x R q_{m5}$
- 12. $q_{m5} \bar{x}_i R q_{m5}$
- 13. $q_{m5} x_i B q_{m6}$
- 14. $q_{m6} \bar{x}_i L q_{m6}$
- 15. $q_{m6} x_i l q_{m7}$
- 16. $q_{m7} l L q_{m7}$
- 17. $q_{m7} B x_i q_{m+1}$
- 18. $q_{m4} l B q_{m8}$
- 19. $q_{m8} \bar{x}_i L q_{m8}$
- 20. $q_{m8} x_i L q_{m9}$
- 21. $q_{m9} l L q_{m9}$
- 22. $q_{m9} \alpha l q_{m10}$
- 23. $q_{m10} l L q_{m10}$
- 24. $q_{m10} B \alpha q_{m2}$

the state q_{m2} .

Looks for the first pointer x_i and then passes to state q_{m3} .

Looks for the second pointer x_i , and then passes to state q_{m4} .

If a digit "|" is not formed in the area corresponding to x_i , eliminates the pointer and passes to state q_{m6} .

Looks for the beginning, put another digit "|" at the new address for x_i , displaces one square left and finally passes to state q_{m+1} .

If a "|" is found in the corresponding area for x_i , erase this |, returns to the beginning of the tape, put another "|" at the new position for x_i , displaces one square left and set back to state q_{m2} .

4. Application of the SLIP languages

In the following we will try to obtain a program that simulates the machine described above; some changes will have to be done with respect to the tape organization the principal difference is that the delimiter will be placed at the beginning of the reserved area. On the other side we will eliminate the wquaduples concerning the displacement of α , because in SLIP the user need not be concerned with the displacements relative to the insertion of nodes. We will use the letters of the alphabet as area delimiters and as the name of the list, in place of α , the symbol \$. The tape organization is showing below:

(\$ (A |||...|) (B ||...|)...(I ||...|)...(N ||..|))

In the program that follows we introduced enough comments to help the understanding of the machine performance.

5. Program Description

```

C**** EXEMPLO 2 - TURING MACHINE
C**** THIS MACHINE CALCULATES THE SUCCESSOR OF THE I-TH COMPONENT OF THE N TUPLE
      (X1,...,XN)
C*****INITIALIZATION
      COMMON AVSL,W(100)
      DIMENSION-SPACE(5000),L(20),IENDCO(20),ITAPE(1000),ICOMP(20)
      INTEGER BLK,UM
      DATA MARK,IENCO/1H$,1HA,1HB,1HC,1HD,1HE,1HF,1HG,1HH,1HI,1HJ,1HK,1
1HL,1HM,1HM,1HN,1HO,1HP,1HQ,1HR,1HS,1HT/,UM,BLK/1HL,1H /
      KKK=5
      IPROJ=IENDCO(KKK)
      N=10
      READ(5,1)(I),I=1,N)
1 FORMAT(16I5)
C**** LIST STRUCTURE
      CALL INITAS(SPACE,5000)

```

```

CALL LIST (LL)
CALL NEWTOP (MARK,LL)
DO 2 I=1,N
2 CALL NEWTOP (IENDCO (I) ,LIST (L (I) ))
DO 3 J=1,N
K=ICOMP (J)
DO 3 I=1,K
3 CALL NEWBOT (UM,L (J) )
DO 4 I=1,N
4 CALL NEWBOT (L (I) ,LL)
M=LRDROV (LL)
DO 5 I=1,1000
ITAPE (I) =INIGER (ADVSR (M,F) )
IF (F) 6,5,6
5 CONTINUE
6 II=I-1
WRITE (6,7) (ITAPE (I) ,I=1,II)
7 FORMAT (//10X,15HTAPE DE ENTRADA,/10X,120A1,/)
C**** STATE QM SEARCHS THE BEGINNING OF THE TAPE
8 LEITOR=INIGER (ADVSEL (M,F) )
IF (LEITOR.NE.MARK)GO TO 8
C**** STATE QM1 (BEGINNING OF THE TAPE FOUND)
LEITOR=INIGER (ADVSEL (M,F) )
CALL POPTOP (LL)
CALL NEWTOP (IPROJ,LIST (L (N+1) ))
CALL NEWTOP (L (N+1) ,LL)
CALL NEWTOP (MARK,LL)
C**** IF IPROJ IS FOUND PASSES TO STATE QM2
9 LEITOR=INIGER (ADVSR (M,F) )
IF (LEITOR.NE.IPROJ)GO TO 9
C**** STATE QM2-LOOKS FOR THE SECOND IPROJ
10 LEITOR=INIGER (ADVSR (M,F) )
IF (F) 9,11,9
11 IF (LEITOR.NE.IPROJ)GO TO 10

```

C**** STATE QM3 FOUND THE SECOND IPROJ,PASSES TO STATE QM4

```

12 LETTOR=INIGER (ADVSR (M,F))
   IF (LETTOR.EQ.BLK)GO TO 12
   IF (LETTOR.EQ.IENDCO (KKK+1))GO TO 15
   IF (F)15,13,15

```

C**** A 1 IS FOUND-SUBSTITUTES BY A BLANK AND PASSES TO STATE QM8

```

13 K1=LPNTR (M)
   LETTOR=INTEGER (ADVSR (M,F))
   CALL SUBST (BLK,K1)
46 LETTOR=INIGER (ADVSEL (M,F))
   IF (F)47,46,47
47 LETTOR=INIGER (ADVSR (M,F))
   LETTOR=INIGER (ADVSEL (M,F))
   CALL NEWBOT (UM,L (N+1))
   IN=LRDROV (LL)
   DO 80 I=1,1000
   ITAPE (I)=INIGER (ADVSR (IN,G))
   IF (G)81,80,81
80 CONTINUE
81 WRITE (6,85) (ITAPE (I),I=1,II)
85 FORMAT (//10X,16HSITUACAO DO TAPE,/10X,120A1)
   GO TO 9
15 LETTOR=INIGER (ADVSEL (M,F))
   IF (LETTOR.NE.MARK)GO TO 15
   LETTOR=INIGER (ADVSR (M,F))
   CALL NEWBOT (UM,L (N+1))
   CALL MLIST (L (KKK))
   M=LRDROV (LL)
   DO 16 I=1,1000
   ITAPE (I)=INIGER (ADVSR (M,F))
   IF (F)17,16,17
16 CONTINUE
17 II=I-1

```



```
WRITE(6,70) (ITAPE(I),I=1,II)
70 FORMAT (//10X,13HTAPE DE SAIDA,/10X,120A1,/)
CALL IRARDR(M)
200 FORMAT(10X ,22HO READER APONTA PARA ,2H**,A1,2H**,/)
CALL EXIT
END
```

6. Conclusions

The method presented here can be used in the construction of any of turing machine, and we found that SNP is a language will adapted for such treatments. Our program is not necessarily the best, but we believe it can be a guide for work.

References

1. Nelson, R.J. "Introduction to Automata" Wiley and Sons, Inc.
2. Rosen, Saul "Programming Systems and Languages" Mc Graw Hill Book Company.