

pends on the solution of a linear system of dimension k . The other states are then obtained by the recurrent relation

$$X_n = H(n) X_{n+1}, \quad n < N.$$

The linear system determining X_N in the general case has somewhat complicated coefficients, but is still tractable. Moreover, we have shown in Section IV how this can be managed in the particular but important case of a service process without feedback.

The generality of the models allows us to pass quite easily from the block-diagram representation of the service process to the Markovian model. This is a major advantage for designers of, for example, computer architectures.

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Corrigenda

Correction to "Specification and Verification of Communication Protocols in AFFIRM Using State Transition Models"

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In the above paper,¹ the following corrections should be noted.

On p. 476, second column: first reference [52] should be [54]; last reference [54] should be [4].

¹C. A. Sunshine *et al.*, *IEEE Trans. Software Eng.*, vol. SE-8, no. 5, pp. 460-489, Sept. 1982.

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